

Resource leveling for scheduling problems: some complexity and approximation results

Luca Brunod Indrigo ^{1, 2} Pascale Bendotti ^{1, 2}
Philippe Chrétienne ² Bruno Escoffier ²

¹EDF R&D

²Sorbonne Université, CNRS, LIP6 UMR 7606

15/04/2026

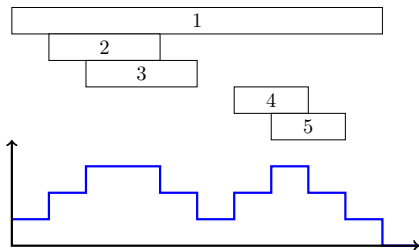
Scheduling Seminar, schedulingseminar.com



- 1 Introduction
- 2 A tractable case
- 3 Some approximation results
- 4 Conclusion

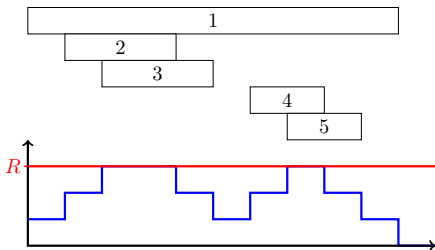
Resource leveling

- Many scheduling problems involve **resources**
- Resources represent workers, equipments, processors. . .



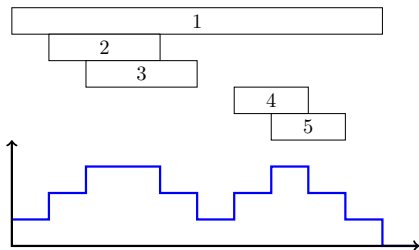
Resource leveling

- Many scheduling problems involve **resources**
- Resources represent workers, equipments, processors. . .
- Resource capacity usually imposed as **hard constraint**
- ex: machine scheduling, RCPSP



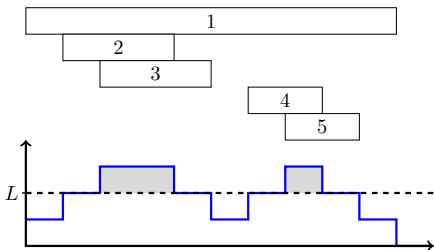
Resource leveling

- In resource leveling, **no hard constraints** on resources
- Objective function penalizes irregularities in resource use



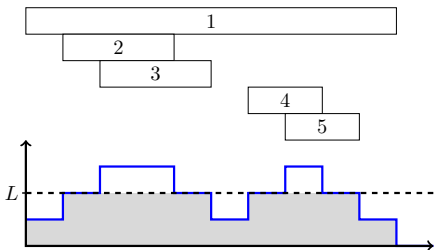
Resource leveling

- In resource leveling, **no hard constraints** on resources
- Objective function penalizes irregularities in resource use
- Total overload cost: **minimizing** the resource use **exceeding a level L**



Resource leveling

- In resource leveling, **no hard constraints** on resources
- Objective function penalizes irregularities in resource use
- Total overload cost: **minimizing** the resource use **exceeding a level L**
- Equivalent to **maximizing** the resource use that **fits under level L**



Resource leveling

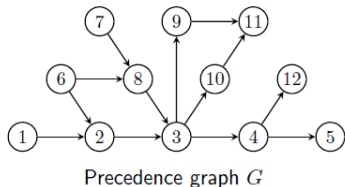
Problems under consideration

- A set of jobs J , with processing times
- A (target) resource level L
- Objective: try not to exceed this level
 - ideally no more than L jobs in parallel
 - Max the load that fits under this level L : function F
- Under a makespan deadline M
- and various constraints or cases, such as:
 - Precedence constraints
 - Unit processing times
 - ...

Resource leveling

Example

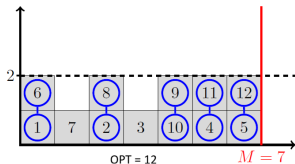
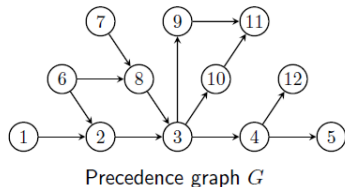
- 12 jobs with processing times $p_i = 1$, with precedence constraints
- Resource level $L = 2$
- Makespan deadline M .



Resource leveling

Example

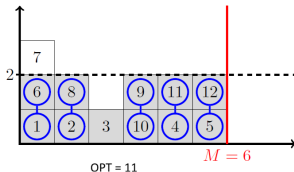
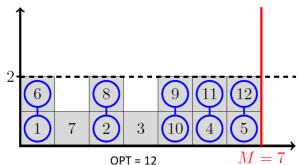
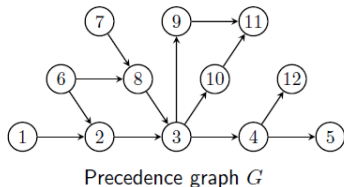
- 12 jobs with processing times $p_i = 1$, with precedence constraints
- Resource level $L = 2$
- Makespan deadline M .



Resource leveling

Example

- 12 jobs with processing times $p_i = 1$, with precedence constraints
- Resource level $L = 2$
- Makespan deadline M .



Resource leveling

Example

- 12 jobs with processing times $p_i = 1$, with precedence constraints
- Resource level $L = 2$
- Makespan deadline M .

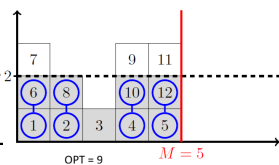
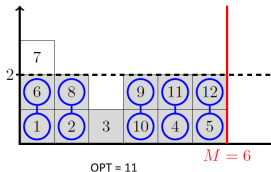
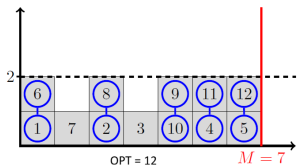
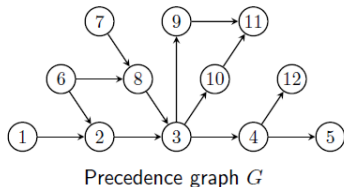


Table of complexity results

		$C_{max} \leq M$	$prec, C_{max} \leq M$		r_i, d_i	
			any	<i>in-tree</i>	no <i>pmtn</i>	<i>pmtn</i>
$L = 1$	\emptyset	in P	in P		strongly NP -hard	in P
$L = 2$	\emptyset	pseudo polynomial	strongly NP -hard		strongly NP -hard	in P
	$p_i = 1$	in P	in P		in P	
$L \in \mathbb{N}$	\emptyset	strongly NP -hard				in P
	$p_i = 1$	in P	strongly NP -hard	in P	in P	

Complexity of resource leveling problems ¹

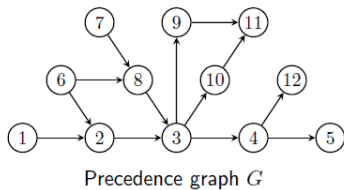
¹Bendotti, Brunod Indrigo, Chrétienne, Escoffier, Journal of Scheduling 2024.

- 1 Introduction
- 2 A tractable case
- 3 Some approximation results
- 4 Conclusion

Resource leveling

$L2|prec, p_i = 1, C_{max} \leq M|F$

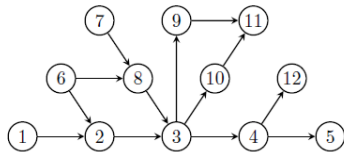
- n jobs with processing times $p_i = 1$, with precedence constraints
- Resource level $L = 2$
- Makespan deadline M .
- Maximize F .



Resource leveling

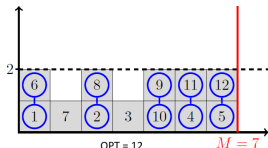
$L2|prec, p_i = 1, C_{max} \leq M|F$

- n jobs with processing times $p_i = 1$, with precedence constraints
- Resource level $L = 2$
- Makespan deadline M .
- Maximize F .



Precedence graph G

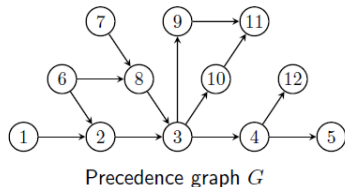
- Q1: can I know if everything can fit or not?
 $\rightarrow OPT = \sum p_i = n?$



Resource leveling

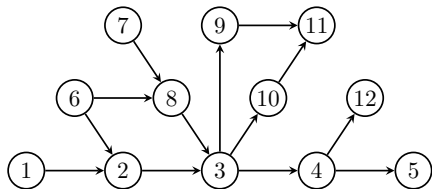
$L2|prec, p_i = 1, C_{max} \leq M|F$

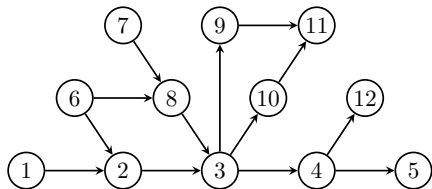
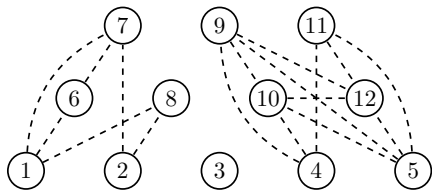
- n jobs with processing times $p_i = 1$, with precedence constraints
- Resource level $L = 2$
- Makespan deadline M .
- Maximize F .

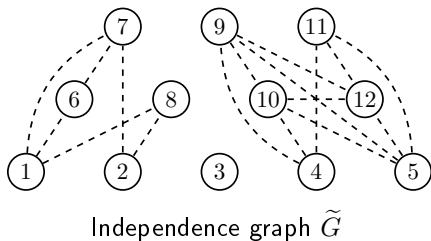
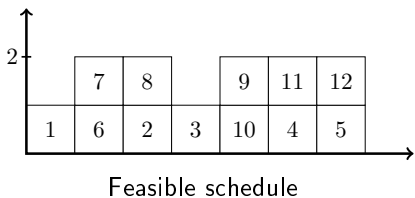


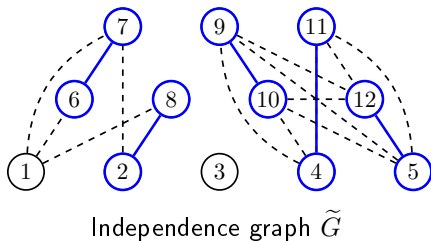
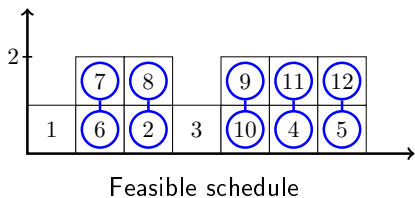
- Q1: can I know if everything can fit or not?
→ $OPT = \sum p_i = n$?

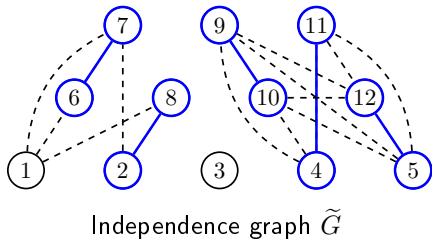
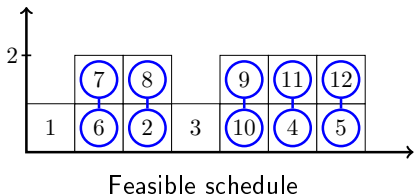
Equivalent to the well-known $P_2|prec, p_i = 1|C_{max}$ problem ...
... solvable in polynomial time (Fujii, Kasami, and Ninomiya (1969)).

Solving Q1, or $P2|prec, p_i = 1|C_{max}$ Precedence graph G

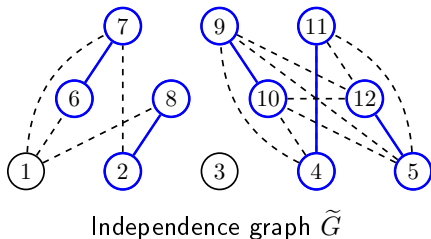
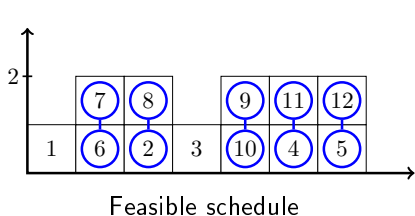
Solving Q1, or $P2|prec, p_i = 1|C_{max}$ Precedence graph G Independence graph \tilde{G}

Solving Q1, or $P2|prec, p_i = 1|C_{max}$ 

Solving Q1, or $P2|prec, p_i = 1|C_{max}$ 

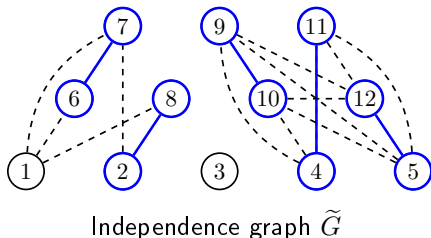
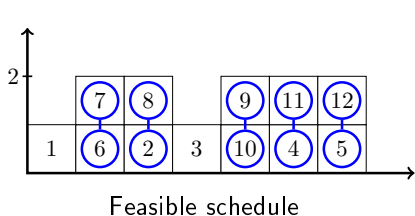
Solving Q1, or $P2|prec, p_i = 1|C_{max}$ 

Schedule of makespan $|J| - m \Rightarrow$ matching of size m in \tilde{G}

Solving Q1, or $P2|prec, p_i = 1|C_{max}$ 

Theorem (Fujii1969)

Schedule of makespan $|J| - m \Leftrightarrow$ matching of size m in \tilde{G}

Solving Q1, or $P2|prec, p_i = 1|C_{max}$ 

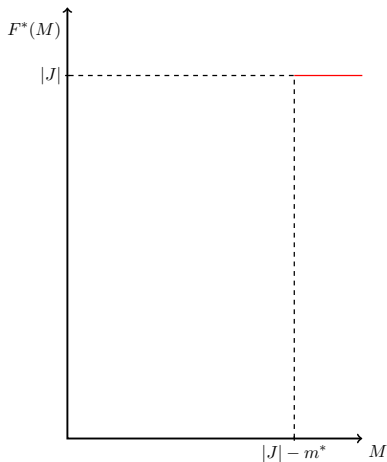
Theorem (Fujii1969)

Schedule of makespan $|J| - m \Leftrightarrow$ matching of size m in \tilde{G}

m^* size of a max matching in $\tilde{G} \Leftrightarrow$ minimum makespan is $|J| - m^*$

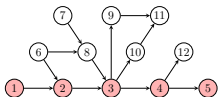
Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

- Q1: when does $OPT = |J|$?
→ When $M \geq |J| - m^*$
using [Fujii et al, 1969]

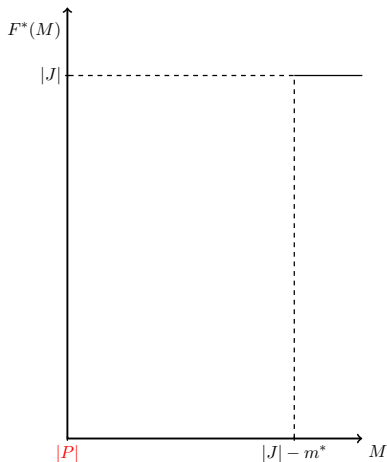


Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

- Q1: when does $OPT = |J|$?
→ When $M \geq |J| - m^*$
using [Fujii et al, 1969]
- Q2
 P critical path in G
No feasible schedules for
 $M < |P|$

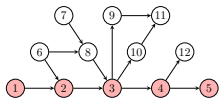


Critical path in precedence graph G



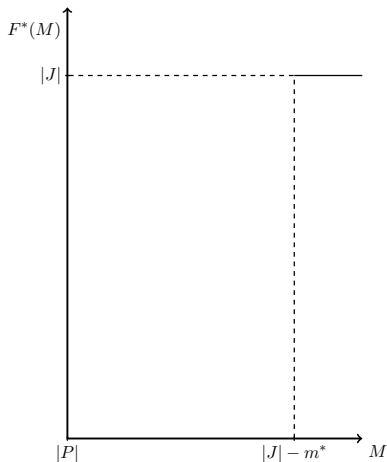
Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

- Q1: when does $OPT = |J|$?
→ When $M \geq |J| - m^*$
using [Fujii et al, 1969]
- Q2
 P critical path in G
No feasible schedules for
 $M < |P|$



Critical path in precedence graph G

→ Q2: can we solve the
problem for $M = |P|$?



Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

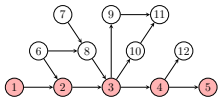
- Q1: when does $OPT = |J|$?

→ When $M \geq |J| - m^*$
using [Fujii et al, 1969]

- Q2

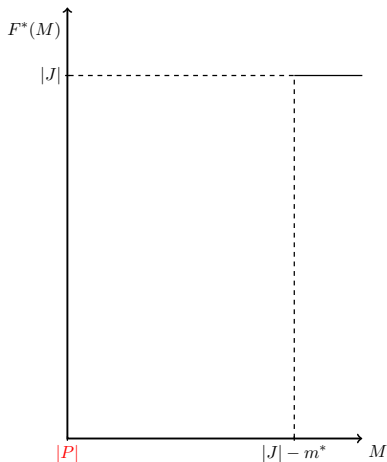
P **critical path** in G

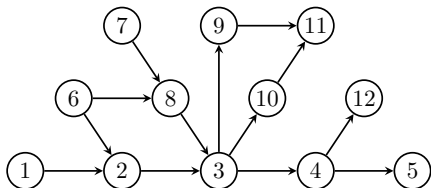
No feasible schedules for
 $M < |P|$

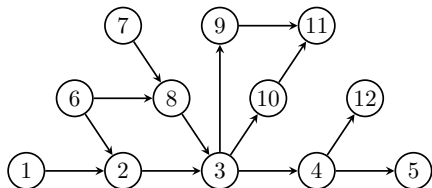
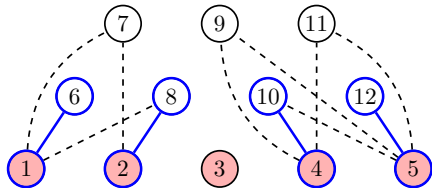


Critical path in precedence graph G

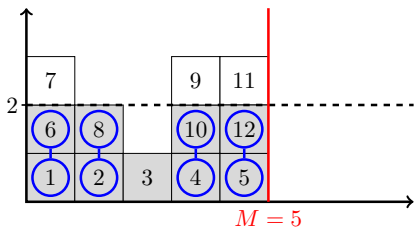
→ Q2: can we solve the
problem for $M = |P|$?



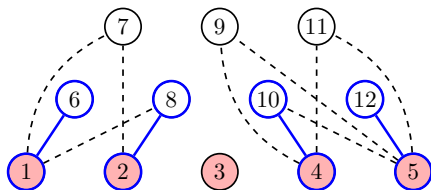
Solving Q2: when $M =$ size of a critical pathPrecedence graph G

Solving Q2: when $M =$ size of a critical pathPrecedence graph G Independence bipartite graph \tilde{G}_P

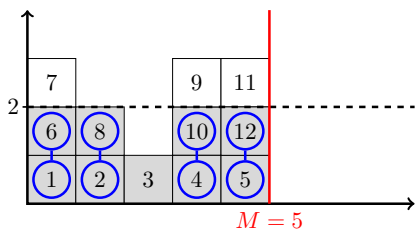
Solving Q2: when $M = \text{size of a critical path}$



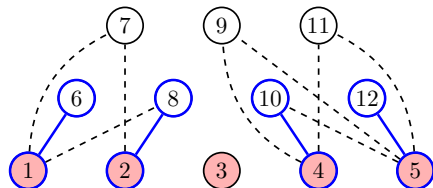
Feasible schedule



Independence bipartite graph \tilde{G}_P

Solving Q2: when $M = \text{size of a critical path}$ 

Feasible schedule

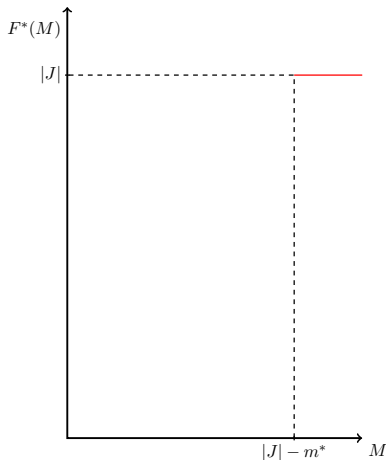
Independence bipartite graph \tilde{G}_P

Theorem (“Fujii-like”)

$OPT = |P| + m_P^*$ where $P = \text{critical path}$ and $m_P^* = \text{size of a max matching in } \tilde{G}_P$.

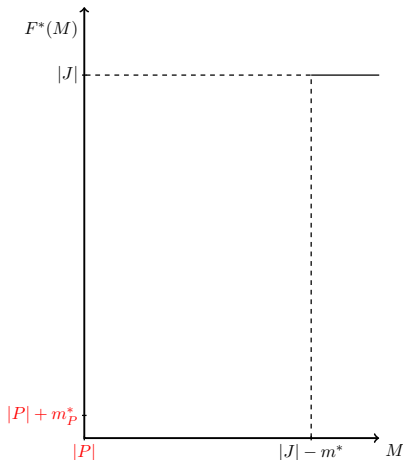
Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

- $M \geq |J| - m^*$: $OPT = |J|$
(Q1, Fujii et al. 1969)



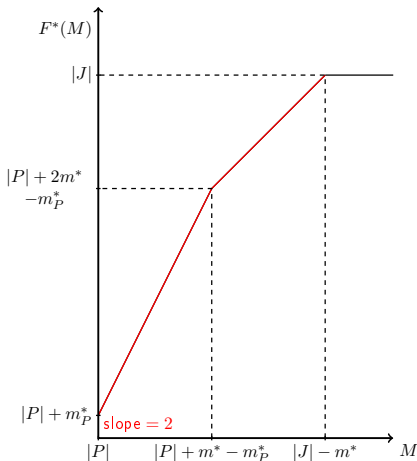
Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

- $M \geq |J| - m^*$: $OPT = |J|$
(Q1, Fujii et al. 1969)
- $M = |P|$: $OPT = |P| + m_P^*$
(Q2, previous slide)
 m_P^* the size of a max
matching in \tilde{G}_P



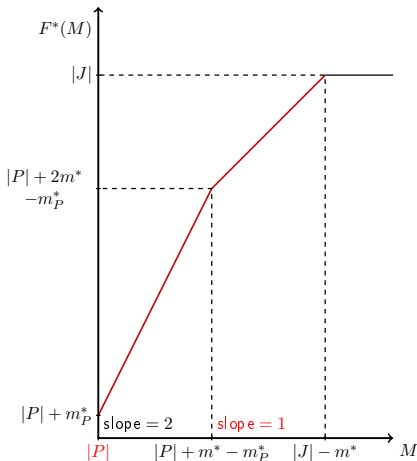
Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

- $M \geq |J| - m^*$: $OPT = |J|$
(Q1, Fujii et al. 1969)
- $M = |P|$: $OPT = |P| + m_P^*$
(Q2, previous slide)
 m_P^* the size of a max
matching in \tilde{G}_P
- $|P| \leq M \leq |P| + m^* - m_P^*$:
optimal objective function
has **slope 2**

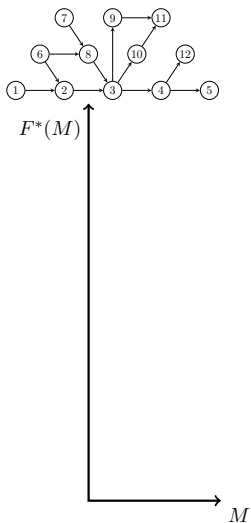


Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

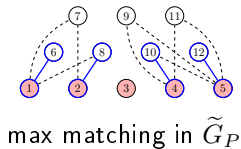
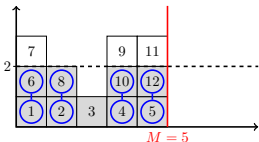
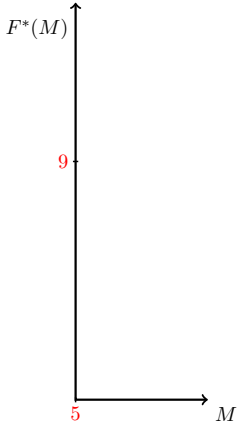
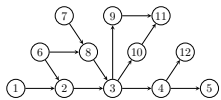
- $M \geq |J| - m^*$: $OPT = |J|$
(Q1, Fujii et al. 1969)
- $M = |P|$: $OPT = |P| + m_P^*$
(Q2, previous slide)
 m_P^* the size of a max
matching in \tilde{G}_P
- $|P| \leq M \leq |P| + m^* - m_P^*$:
optimal objective function
has slope 2
- $|P| + m^* - m_P^* \leq M \leq$
 $|J| - m^*$: optimal objective
function has **slope 1**



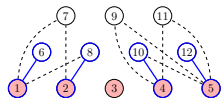
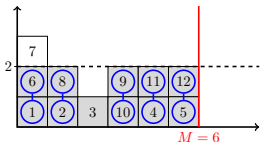
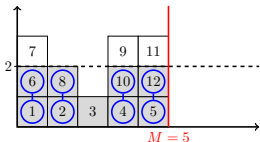
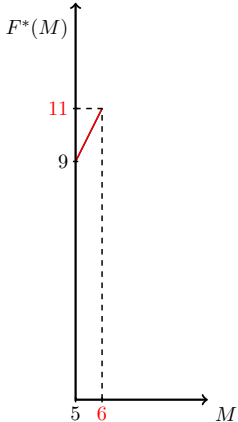
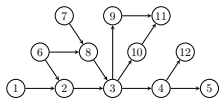
Example



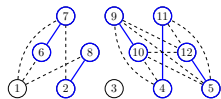
Example



Example

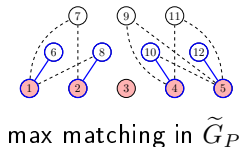
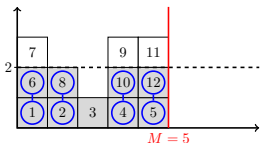
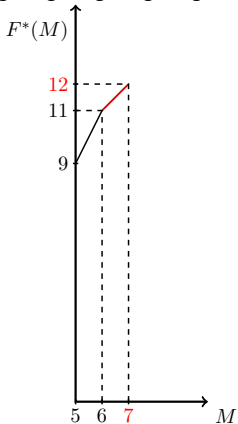
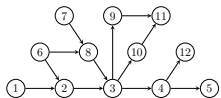


max matching in \tilde{G}_P

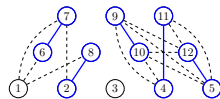
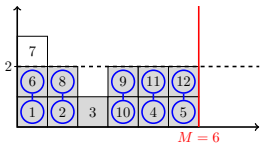


max matching in \tilde{G}

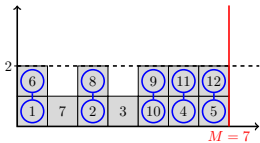
Example



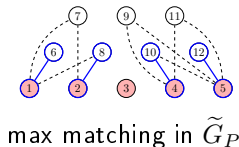
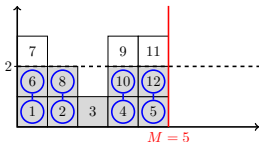
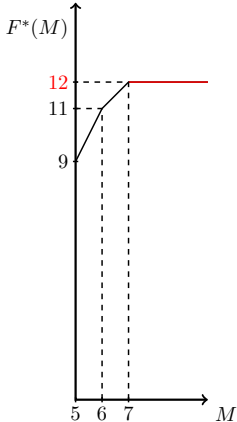
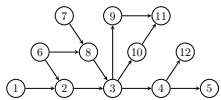
max matching in \tilde{G}_P



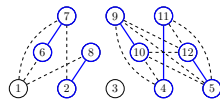
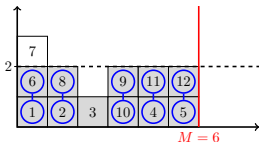
max matching in \tilde{G}



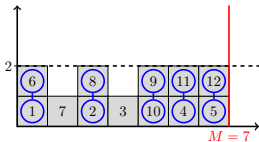
Example



max matching in \tilde{G}_P



max matching in \tilde{G}



Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

Theorem

$L2|prec, p_i = 1, C_{max} \leq M|F$ is polynomial-time solvable

Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

Theorem

$L2|prec, p_i = 1, C_{max} \leq M|F$ is polynomial-time solvable

Question

What about non unit processing time?

Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

Theorem

$L2|prec, p_i = 1, C_{max} \leq M|F$ is polynomial-time solvable

Question

What about non unit processing time?

The problem becomes strongly NP-hard

Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

Theorem

$L2|prec, p_i = 1, C_{max} \leq M|F$ is polynomial-time solvable

Question

What about non unit processing time?

The problem becomes strongly NP-hard

Question

What about $L = 3$ (with $p_i = 1$)?

Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

Theorem

$L2|prec, p_i = 1, C_{max} \leq M|F$ is polynomial-time solvable

Question

What about non unit processing time?

The problem becomes strongly NP-hard

Question

What about $L = 3$ (with $p_i = 1$)?

It is an open question!

Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

Theorem

$L2|prec, p_i = 1, C_{max} \leq M|F$ is polynomial-time solvable

Question

What about non unit processing time?

The problem becomes strongly NP-hard

Question

What about $L = 3$ (with $p_i = 1$)?

It is an open question!

$L3|prec, p_i = 1, C_{max} \leq M|F$ is strongly related to machine scheduling problem $P3|prec, p_i = 1|C_{max} \dots$

Solving $L2|prec, p_i = 1, C_{max} \leq M|F$

Theorem

$L2|prec, p_i = 1, C_{max} \leq M|F$ is polynomial-time solvable

Question

What about non unit processing time?

The problem becomes strongly NP-hard

Question

What about $L = 3$ (with $p_i = 1$)?

It is an open question!

$L3|prec, p_i = 1, C_{max} \leq M|F$ is strongly related to machine scheduling problem $P3|prec, p_i = 1|C_{max} \dots$ which is of **unknown complexity!**

- 1 Introduction
- 2 A tractable case
- 3 Some approximation results
- 4 Conclusion

Table of complexity results

		$C_{max} \leq M$	$prec, C_{max} \leq M$		r_i, d_i	
			\emptyset	<i>in-tree</i>	no <i>pmtn</i>	<i>pmtn</i>
$L = 1$	\emptyset	<i>in P</i>	<i>in P</i>		strongly NP-hard	<i>in P</i>
$L = 2$	\emptyset	pseudo polynomial	strongly NP-hard		strongly NP-hard	<i>in P</i>
	$p_i = 1$	<i>in P</i>	in P	<i>in P</i>		
$L \in \mathbb{N}$	\emptyset	strongly NP-hard				<i>in P</i>
	$p_i = 1$	<i>in P</i>	strongly NP-hard	<i>in P</i>	<i>in P</i>	

Complexity of resource leveling problems ²

²Bendotti, Brunod Indrigo, Chrétienne, Escoffier, Journal of Scheduling 2024.

Approximation results

Polynomial cases are restrictive

³Complexity $f(\epsilon)p(n)$. A PTAS can be deduced from [Györgyi, Kis, EJOR 2020]

⁴if $NP \not\subseteq \bigcap_{\epsilon>0} BPTIME(2^{n^\epsilon})$

⁵Bendotti, Brunod Indrigo, Chrétienne, Escoffier, Theoretical Computer Science 2025.

Approximation results

Polynomial cases are restrictive \rightarrow improved tractability of more realistic yet NP -hard cases through approximation results

³Complexity $f(\epsilon)p(n)$. A PTAS can be deduced from [Györgyi, Kis, EJOR 2020]

⁴if $NP \not\subseteq \bigcap_{\epsilon>0} BPTIME(2^{n^\epsilon})$

⁵Bendotti, Brunod Indrigo, Chrétienne, Escoffier, Theoretical Computer Science 2025.

Approximation results

Polynomial cases are restrictive → improved tractability of more realistic yet NP -hard cases through approximation results

	$C_{max} \leq M$	$C_{max} \leq M, prec$	
		\emptyset	<i>in-tree</i>
$L = 2$	(str.) NP -hard	str. NP -hard	
$L = 3$		str. NP -hard	
$L \in \mathbb{N}$		str. NP -hard	str. NP -hard

Approximation of resource leveling problems⁵

³Complexity $f(\epsilon)p(n)$. A PTAS can be deduced from [Györgyi, Kis, EJOR 2020]

⁴if $NP \not\subseteq \bigcap_{\epsilon > 0} BPTIME(2^{n^\epsilon})$

⁵Bendotti, Brunod Indrigo, Chrétienne, Escoffier, Theoretical Computer Science 2025.

Approximation results

Polynomial cases are restrictive → improved tractability of more realistic yet NP -hard cases through approximation results

	$C_{max} \leq M$	$C_{max} \leq M, prec$	
		\emptyset	<i>in-tree</i>
$L = 2$	(str.) NP -hard	str. NP -hard ratio $\frac{2}{3}$	
$L = 3$	EPTAS ³ ratio $\frac{7}{8}$ in	str. NP -hard ratio $\frac{3}{5}$	
$L \in \mathbb{N}$	$O(J \log(J))$	str. NP -hard No PTAS ⁴	str. NP -hard ratio $\frac{1}{2}$

Approximation of resource leveling problems⁵

³Complexity $f(\epsilon)p(n)$. A PTAS can be deduced from [Györgyi, Kis, EJOR 2020]

⁴if $NP \not\subseteq \bigcap_{\epsilon > 0} BPTIME(2^{n^\epsilon})$

⁵Bendotti, Brunod Indrigo, Chrétienne, Escoffier, Theoretical Computer Science 2025.

Inapproximability

Proposition

$L|_{prec, C_{max} \leq M}|F$ admits no PTAS under a classical complexity assumption.

Inapproximability

Proposition

$L|bipartite, p_i = 1, C_{max} \leq 3|F$ admits no PTAS under a classical complexity assumption.

- Holds even if $prec = bipartite$, $p_i = 1$ and $M = 3$

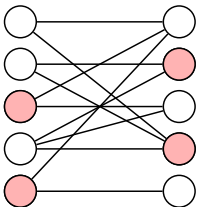
Inapproximability

Proposition

$L|_{bipartite, p_i = 1, C_{max} \leq 3|F}$ admits no PTAS under a classical complexity assumption.

- Holds even if $prec = bipartite$, $p_i = 1$ and $M = 3$
- Reduction from a Balanced Bipartite Independent Set Problem (Khot2006)

Inapproximability

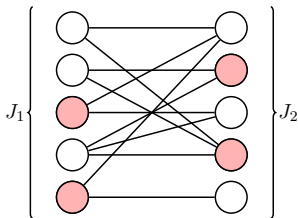


Independent Set

Find a set S , $|S| \geq k$, of pairwise non adjacent vertices

- Hard problem (hard to approximate as well)
- Easy in bipartite graph ...

Inapproximability



Independent Set

Find a set S , $|S| \geq k$, of pairwise non adjacent vertices

- Hard problem (hard to approximate as well)
- Easy in bipartite graph ...
- ... Balanced version is hard: find an IS S with $|S \cap J_1| \geq k$ and $|S \cap J_2| \geq k$.
No PTAS under some complexity assumption ((Khot2006)).

Inapproximability

Proposition

$L|bipartite, p_i = 1, C_{max} \leq 3|F$ admits no PTAS under a classical complexity assumption.

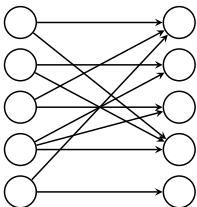
- Holds even if $prec = bipartite, p_i = 1$ and $M = 3$
- Reduction from a Balanced Bipartite Independent Set Problem (Khot2006)

Inapproximability

Proposition

$L|bipartite, p_i = 1, C_{max} \leq 3|F$ admits no PTAS under a classical complexity assumption.

- Holds even if $prec = bipartite, p_i = 1$ and $M = 3$
- Reduction from a Balanced Bipartite Independent Set Problem (Khot2006)

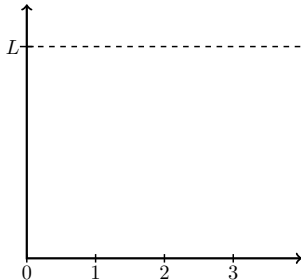
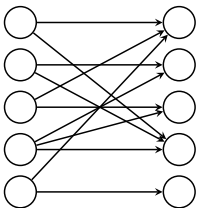


Inapproximability

Proposition

$L|bipartite, p_i = 1, C_{max} \leq 3|F$ admits no PTAS under a classical complexity assumption.

- Holds even if $prec = bipartite$, $p_i = 1$ and $M = 3$
- Reduction from a Balanced Bipartite Independent Set Problem (Khot2006)

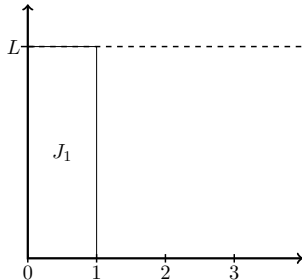
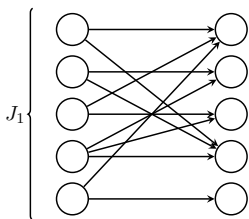


Inapproximability

Proposition

$L|bipartite, p_i = 1, C_{max} \leq 3|F$ admits no PTAS under a classical complexity assumption.

- Holds even if $prec = bipartite$, $p_i = 1$ and $M = 3$
- Reduction from a Balanced Bipartite Independent Set Problem (Khot2006)

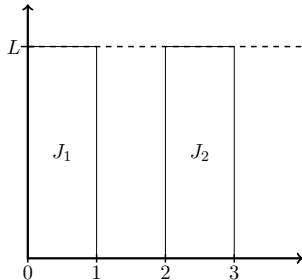
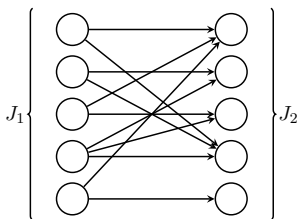


Inapproximability

Proposition

$L|bipartite, p_i = 1, C_{max} \leq 3|F$ admits no PTAS under a classical complexity assumption.

- Holds even if $prec = bipartite$, $p_i = 1$ and $M = 3$
- Reduction from a Balanced Bipartite Independent Set Problem (Khot2006)

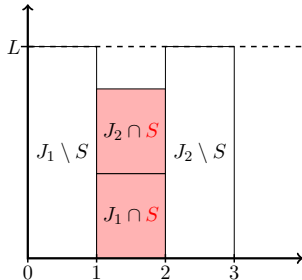
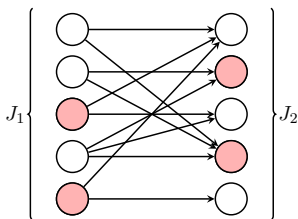


Inapproximability

Proposition

$L|bipartite, p_i = 1, C_{max} \leq 3|F$ admits no PTAS under a classical complexity assumption.

- Holds even if $prec = bipartite$, $p_i = 1$ and $M = 3$
- Reduction from a Balanced Bipartite Independent Set Problem (Khot2006)



Approximation results

	$C_{max} \leq M$	$C_{max} \leq M, prec$	
		\emptyset	<i>in-tree</i>
$L = 2$	str. NP-hard EPTAS ratio $\frac{7}{8}$ in $O(J \log(J))$	str. NP-hard ratio $\frac{2}{3}$	
$L = 3$		str. NP-hard ratio $\frac{3}{5}$	
$L \in \mathbb{N}$		str. NP-hard No PTAS ⁶	str. NP-hard ratio $\frac{1}{2}$

Approximation of resource leveling problems⁷

⁶if $NP \not\subseteq \bigcap_{\epsilon > 0} BPTIME(2^{n^\epsilon})$

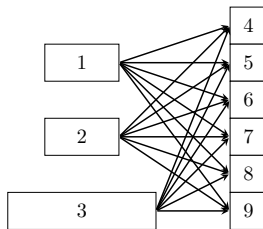
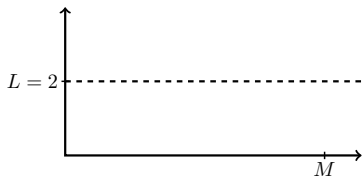
⁷Bendotti, Brunod Indrigo, Chrétienne, Escoffier, Theoretical Computer Science 2025.

$L|prec, C_{max} \leq M|F$: A list algorithm

A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm

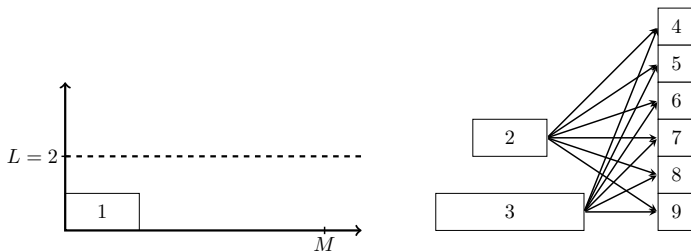
$L|prec, C_{max} \leq M|F$: A list algorithm

A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm



$L|prec, C_{max} \leq M|F$: A list algorithm

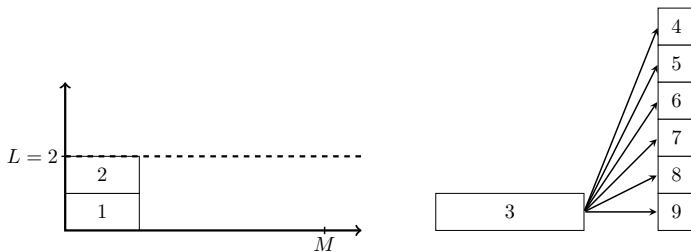
A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm



- Jobs scheduled in a topological order

$L|prec, C_{max} \leq M|F$: A list algorithm

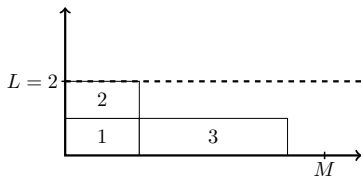
A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm



- Jobs scheduled in a topological order

$L|prec, C_{max} \leq M|F$: A list algorithm

A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm

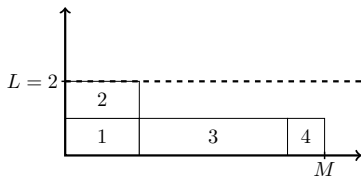


4
5
6
7
8
9

- Jobs scheduled in a topological order
- Trying not to exceed L

$L|prec, C_{max} \leq M|F$: A list algorithm

A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm

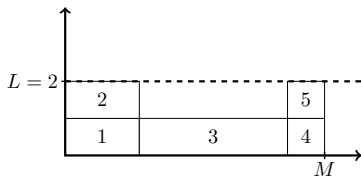


5
6
7
8
9

- Jobs scheduled in a topological order
- Trying not to exceed L

$L|prec, C_{max} \leq M|F$: A list algorithm

A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm

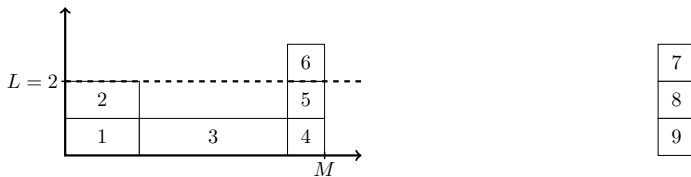


6
7
8
9

- Jobs scheduled in a topological order
- Trying not to exceed L

$L|prec, C_{max} \leq M|F$: A list algorithm

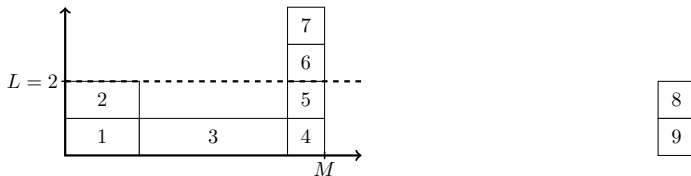
A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm



- Jobs scheduled in a topological order
- Trying not to exceed L
- Exceeding L when forced by a critical path

$L|prec, C_{max} \leq M|F$: A list algorithm

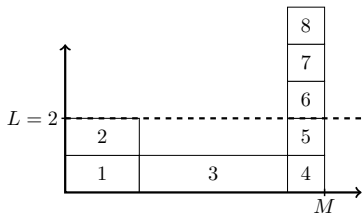
A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm



- Jobs scheduled in a topological order
- Trying not to exceed L
- Exceeding L when forced by a critical path

$L|prec, C_{max} \leq M|F$: A list algorithm

A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm

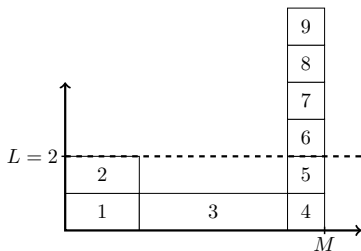


9

- Jobs scheduled in a topological order
- Trying not to exceed L
- Exceeding L when forced by a critical path

$L|prec, C_{max} \leq M|F$: A list algorithm

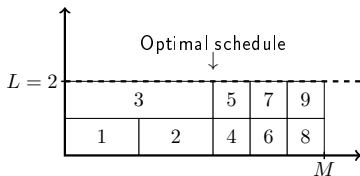
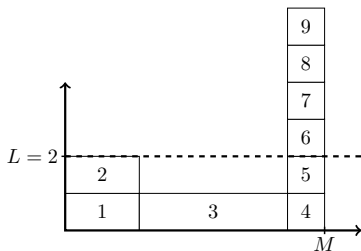
A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm



- Jobs scheduled in a topological order
- Trying not to exceed L
- Exceeding L when forced by a critical path

$L|prec, C_{max} \leq M|F$: A list algorithm

A feasible solution for $L|prec, C_{max} \leq M|F$ can be built using a simple list algorithm



- Jobs scheduled in a topological order
- Trying not to exceed L
- Exceeding L when forced by a critical path
- Not optimal

Approximation of $L2|prec, C_{max} \leq M|F$

Lemma

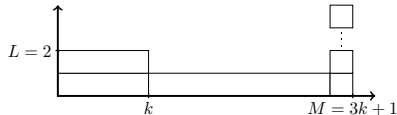
The list algorithm has approximation ratio **at most** $\frac{2}{3}$ for
 $L2|prec, C_{max} \leq M|F$

Approximation of $L2|prec, C_{max} \leq M|F$

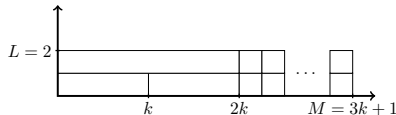
Lemma

The list algorithm has approximation ratio **at most** $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Idea of proof:



List algorithm schedule



Optimal schedule

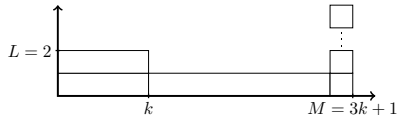
- For $k \in \mathbb{N}$, there is an instance with approximation ratio $\frac{2k+1}{3k+1}$

Approximation of $L2|prec, C_{max} \leq M|F$

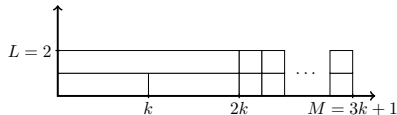
Lemma

The list algorithm has approximation ratio **at most** $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Idea of proof:



List algorithm schedule



Optimal schedule

- For $k \in \mathbb{N}$, there is an instance with approximation ratio $\frac{2k+1}{3k+1}$
- The ratio can be arbitrarily close to $\frac{2}{3}$ for large k

Approximation of $L2|prec, C_{max} \leq M|F$

Lemma

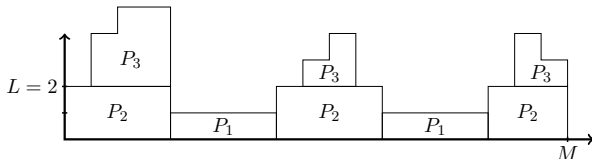
The list algorithm has approximation ratio at least $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Approximation of $L2|prec, C_{max} \leq M|F$

Lemma

The list algorithm has approximation ratio at least $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Idea of proof:

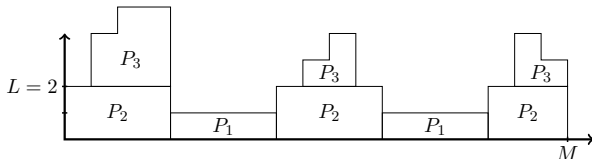


Approximation of $L2|prec, C_{max} \leq M|F$

Lemma

The list algorithm has approximation ratio at least $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Idea of proof:



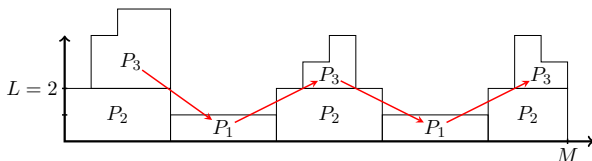
- $F(x) = P_1 + P_2$

Approximation of $L2|prec, C_{max} \leq M|F$

Lemma

The list algorithm has approximation ratio at least $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Idea of proof:



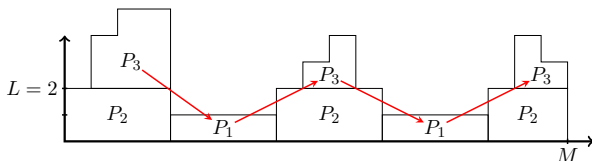
- $F(x) = P_1 + P_2$
- Impossible to schedule P_1 and P_3 in parallel due to precedence constraints $\Rightarrow F^* \leq F(x) + P_2$

Approximation of $L2|prec, C_{max} \leq M|F$

Lemma

The list algorithm has approximation ratio at least $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Idea of proof:



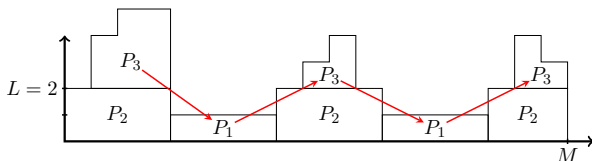
- $F(x) = P_1 + P_2$
- Impossible to schedule P_1 and P_3 in parallel due to precedence constraints $\Rightarrow F^* \leq F(x) + P_2$
- Natural bound: $F^* \leq 2M = P_2 + 2P_1$

Approximation of $L2|prec, C_{max} \leq M|F$

Lemma

The list algorithm has approximation ratio at least $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Idea of proof:



- $F(x) = P_1 + P_2$
- Impossible to schedule P_1 and P_3 in parallel due to precedence constraints $\Rightarrow F^* \leq F(x) + P_2$
- Natural bound: $F^* \leq 2M = P_2 + 2P_1$
- Summing up to: $2F^* \leq 3F(x)$

Approximation of $L2|prec, C_{max} \leq M|F$

Proposition

The list algorithm has (tight) approximation ratio $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Approximation of $L2|prec, C_{max} \leq M|F$

Proposition

The list algorithm has (tight) approximation ratio $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Question

What about $L = 3$?

Approximation of $L2|prec, C_{max} \leq M|F$

Proposition

The list algorithm has (tight) approximation ratio $\frac{2}{3}$ for $L2|prec, C_{max} \leq M|F$

Question

What about $L = 3$?

Proposition

The list algorithm has (tight) approximation ratio $\frac{5}{3}$ for $L3|prec, C_{max} \leq M|F$

Approximation of $L3|prec, C_{max} \leq M|F$

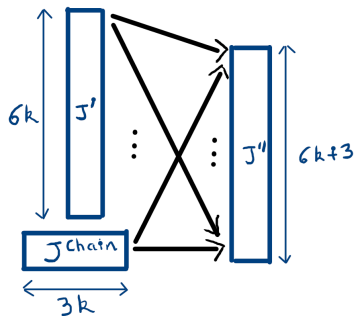
Lemma

The list algorithm has approximation ratio **at most** $\frac{3}{5}$ for $L3|prec, C_{max} \leq M|F$

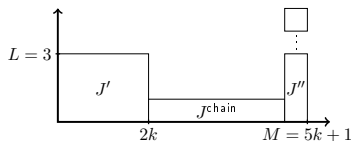
Approximation of $L3|prec, C_{max} \leq M|F$

Lemma

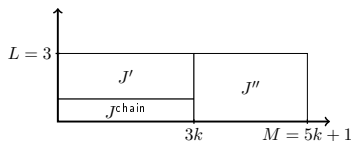
The list algorithm has approximation ratio **at most** $\frac{3}{5}$ for $L3|prec, C_{max} \leq M|F$



Instance



List algorithm schedule



Optimal schedule

Approximation of $L3|prec, C_{max} \leq M|F$

Lemma

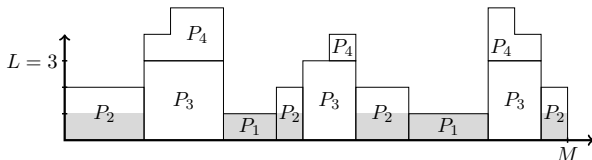
The list algorithm has approximation ratio **at least** $\frac{3}{5}$ for $L2|prec, C_{max} \leq M|F$

Approximation of $L3|prec, C_{max} \leq M|F$

Lemma

The list algorithm has approximation ratio **at least** $\frac{3}{5}$ for $L2|prec, C_{max} \leq M|F$

Proof also based on volume of groups of tasks (but more involved!)



- 1 Introduction
- 2 A tractable case
- 3 Some approximation results
- 4 Conclusion

Conclusion

		$C_{max} \leq M$	$prec, C_{max} \leq M$		r_i, d_i	
			\emptyset	<i>in-tree</i>	<i>no pmtn</i>	<i>pmtn</i>
$L = 1$	\emptyset	<i>in P</i>	<i>in P</i>		<i>strongly NP-hard</i>	<i>in P</i>
$L = 2$	\emptyset	<i>pseudo polynomial</i>	<i>strongly NP-hard</i>	<i>strongly NP-hard</i>	<i>strongly NP-hard</i>	<i>in P</i>
	$p_i = 1$	<i>in P</i>	<i>in P</i>	<i>in P</i>		
$L \in \mathbb{N}$	\emptyset	<i>strongly NP-hard</i>				<i>in P</i>
	$p_i = 1$	<i>in P</i>	<i>strongly NP-hard</i>	<i>in P</i>	<i>in P</i>	

Complexity of resource leveling problems ²

		$C_{max} \leq M$	$C_{max} \leq M, prec$	
			\emptyset	<i>in-tree</i>
$L = 2$		<i>str. NP-hard</i>	<i>str. NP-hard</i> $\frac{2}{3}$ ratio	
$L = 3$			<i>str. NP-hard</i> $\frac{3}{5}$ ratio	
$L \in \mathbb{N}$	$O(J \log(J))$	$\frac{7}{8}$ ratio in EPTAS	<i>str. NP-hard</i> No PTAS ³	<i>str. NP-hard</i> $\frac{1}{2}$ ratio

Approximation of resource leveling problems⁴

Conclusion

	$C_{max} \leq M$	$prec, C_{max} \leq M$		r_i, d_i	
		\emptyset	<i>in-tree</i>	<i>no pmtn</i>	<i>pmtn</i>
$L = 1$	\emptyset	<i>in P</i>	<i>in P</i>	<i>strongly NP-hard</i>	<i>in P</i>
$L = 2$	\emptyset	<i>pseudo polynomial</i>	<i>strongly NP-hard</i>	<i>strongly NP-hard</i>	<i>in P</i>
	$p_i = 1$	<i>in P</i>	<i>in P</i>		<i>in P</i>
$L \in \mathbb{N}$	\emptyset	<i>strongly NP-hard</i>			<i>in P</i>
	$p_i = 1$	<i>in P</i>	<i>strongly NP-hard</i>	<i>in P</i>	<i>in P</i>

Complexity of resource leveling problems ²

	$C_{max} \leq M$	$C_{max} \leq M, prec$	
		\emptyset	<i>in-tree</i>
$L = 2$	<i>str. NP-hard</i>	<i>str. NP-hard</i> $\frac{2}{3}$ ratio	
$L = 3$	<i>EPTAS</i> $\frac{7}{8}$ ratio in	<i>str. NP-hard</i> $\frac{3}{5}$ ratio	
$L \in \mathbb{N}$	$O(J \log(J))$	<i>str. NP-hard</i> No PTAS ³	<i>str. NP-hard</i> $\frac{1}{2}$ ratio

Approximation of resource leveling problems⁴

Some open questions

- Complexity of $L3|prec, p_i = 1, C_{max} \leq M|F$
- Is $L|prec, C_{max} \leq M|F$ approximable within constant ratio?
- Improved ratios (PTAS?) for $L = 2, 3, \dots$?

Conclusion

Resource Leveling?

$$L|prec, C_{max} \leq M|F$$

Conclusion

Resource Leveling?

$$L|prec, C_{max} \leq M|F$$

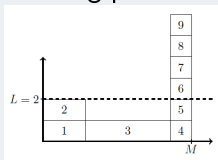
- Function F only penalizes the amount of resource overload

Conclusion

Resource Leveling?

$$L|prec, C_{max} \leq M|F$$

- Function F only penalizes the amount of resource overload
- Nothing prevents variations or high peaks in resource use

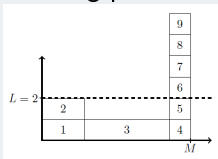


Conclusion

Resource Leveling?

$$L|prec, C_{max} \leq M|?$$

- Function F only penalizes the amount of resource overload
- Nothing prevents variations or high peaks in resource use



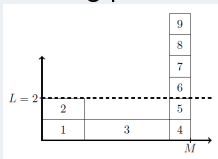
- Other objective functions penalize such behaviors (e.g., resource investment cost, squared changes in resource request)

Conclusion

Resource Leveling?

$$L|prec, C_{max} \leq M|?$$

- Function F only penalizes the amount of resource overload
- Nothing prevents variations or high peaks in resource use



- Other objective functions penalize such behaviors (e.g., resource investment cost, squared changes in resource request)
- Bi-objective problems could be considered to combine resource leveling with another objective (e.g., maximum resource use)

Thank you 😊

$L|C_{max} \leq M|F$: Efficient PTAS

Configuration LP

- Configuration: description per machine/resource unit, with job types
 - Config c_1 : 3 jobs of proc. time 2 and 4 jobs of proc. time 4.
 - Set $\mathcal{C} = \{c_1, \dots, c_p\}$ of possible config. per resource unit.

$L|C_{max} \leq M|F$: Efficient PTAS

Configuration LP

- Configuration: description per machine/resource unit, with job types
 - Config c_1 : 3 jobs of proc. time 2 and 4 jobs of proc. time 4.
 - Set $\mathcal{C} = \{c_1, \dots, c_p\}$ of possible config. per resource unit.
- Solution = $x_i, i = 1 \dots p$: number of config c_i used.
 - $\sum x_i = L$
- ILP: (integer) variables x_i

$L|C_{max} \leq M|F$: Efficient PTAS

Configuration LP

- Configuration: description per machine/resource unit, with job types
 - Config c_1 : 3 jobs of proc. time 2 and 4 jobs of proc. time 4.
 - Set $\mathcal{C} = \{c_1, \dots, c_p\}$ of possible config. per resource unit.
- Solution = $x_i, i = 1 \dots p$: number of config c_i used.
 - $\sum x_i = L$
- ILP: (integer) variables x_i

To work we need to bound p :

- Bound the number of different processing times
- Bound the number of jobs per machine

$L|C_{max} \leq M|F$: Efficient PTAS

Configuration LP

- Configuration: description per machine/resource unit, with job types
 - Config c_1 : 3 jobs of proc. time 2 and 4 jobs of proc. time 4.
 - Set $\mathcal{C} = \{c_1, \dots, c_p\}$ of possible config. per resource unit.
- Solution = $x_i, i = 1 \dots p$: number of config c_i used.
 - $\sum x_i = L$
- ILP: (integer) variables x_i

To work we need to bound p :

- Bound the number of different processing times
- Bound the number of jobs per machine

as a function of ϵ for $(1 - \epsilon)$ -approximation algorithm.

$L|C_{max} \leq M|F$: Efficient PTAS

To work we need to bound p :

- Bound the number of different processing times
- Bound the number of jobs per machine

as a function of ϵ for $(1 - \epsilon)$ -approximation algorithm.

$L|C_{max} \leq M|F$: Efficient PTAS

To work we need to bound p :

- Bound the number of different processing times
- Bound the number of jobs per machine

as a function of ϵ for $(1 - \epsilon)$ -approximation algorithm.

For $L|C_{max} \leq M|F$:

- Reformulate the problem \rightarrow “resource unit view”

$L|C_{max} \leq M|F$: Efficient PTAS

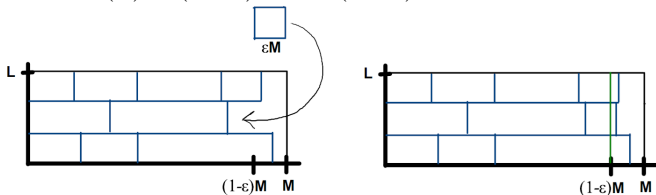
To work we need to bound p :

- Bound the number of different processing times
- Bound the number of jobs per machine

as a function of ϵ for $(1 - \epsilon)$ -approximation algorithm.

For $L|C_{max} \leq M|F$:

- Reformulate the problem \rightarrow “resource unit view”
- Small jobs, $p_i \leq \epsilon M$: can be removed and dealt with later
 - Either there is a spot of $\epsilon M \rightarrow$ put the job.
 - Or ... $F(S) \geq (1 - \epsilon)ML \geq (1 - \epsilon)OPT$.



$L|C_{max} \leq M|F$: Efficient PTAS

To work we need to bound p :

- Bound the number of different processing times
- Bound the number of jobs per machine

as a function of ϵ for $(1 - \epsilon)$ -approximation algorithm.

For $L|C_{max} \leq M|F$:

- Reformulate the problem \rightarrow “resource unit view”
- Small jobs, $p_i \leq \epsilon M$: can be removed and dealt with later
 - Either there is a spot of $\epsilon M \rightarrow$ put the job.
 - Or ... $F(S) \geq (1 - \epsilon)ML \geq (1 - \epsilon)OPT$.
- Now $p_i \geq \epsilon M \rightarrow$ so at most $1/\epsilon$ jobs per resource unit.

$L|C_{max} \leq M|F$: Efficient PTAS

To work we need to bound p :

- Bound the number of different processing times
- Bound the number of jobs per machine

as a function of ϵ for $(1 - \epsilon)$ -approximation algorithm.

For $L|C_{max} \leq M|F$:

- Reformulate the problem \rightarrow “resource unit view”
- Small jobs, $p_i \leq \epsilon M$: can be removed and dealt with later
 - Either there is a spot of $\epsilon M \rightarrow$ put the job.
 - Or ... $F(S) \geq (1 - \epsilon)ML \geq (1 - \epsilon)OPT$.
- Now $p_i \geq \epsilon M \rightarrow$ so at most $1/\epsilon$ jobs per resource unit.
- Round the p_i :
 $(1 - \epsilon)^k M \leq p_i < (1 - \epsilon)^{k-1} M \rightarrow \tilde{p}_i = (1 - \epsilon)^k M$.

$L|C_{max} \leq M|F$: Efficient PTAS

To work we need to bound p :

- Bound the number of different processing times
- Bound the number of jobs per machine

as a function of ϵ for $(1 - \epsilon)$ -approximation algorithm.

For $L|C_{max} \leq M|F$:

- Reformulate the problem \rightarrow “resource unit view”
- Small jobs, $p_i \leq \epsilon M$: can be removed and dealt with later
 - Either there is a spot of $\epsilon M \rightarrow$ put the job.
 - Or ... $F(S) \geq (1 - \epsilon)ML \geq (1 - \epsilon)OPT$.

• Now $p_i \geq \epsilon M \rightarrow$ so at most $1/\epsilon$ jobs per resource unit.

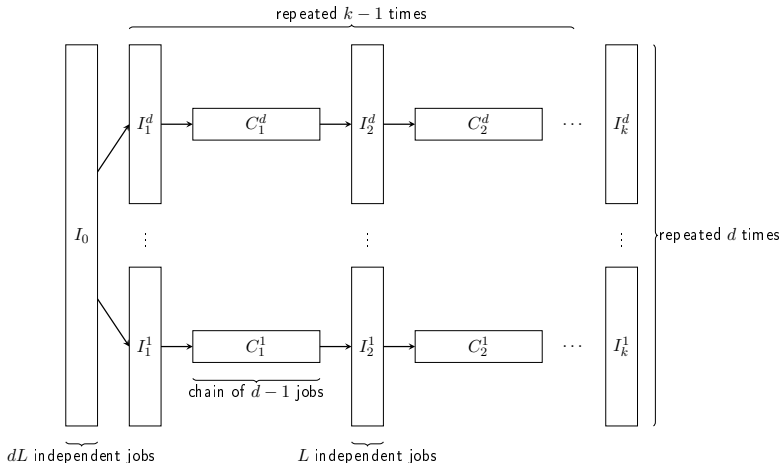
• Round the p_i :

$$(1 - \epsilon)^k M \leq p_i < (1 - \epsilon)^{k-1} M \rightarrow \tilde{p}_i = (1 - \epsilon)^k M.$$

\rightarrow factor $(1 - \epsilon)$ in the rounding

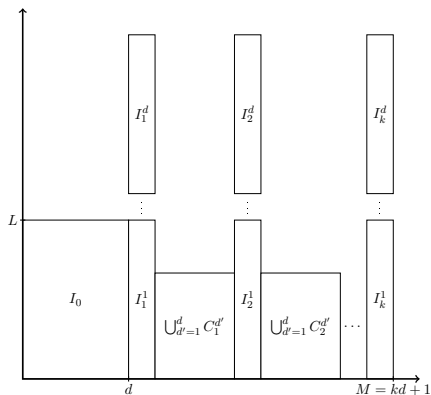
$\rightarrow \sim \log_{1-\epsilon}(\epsilon)$ different processing times.

Bad list algorithm approximation ratio for large L

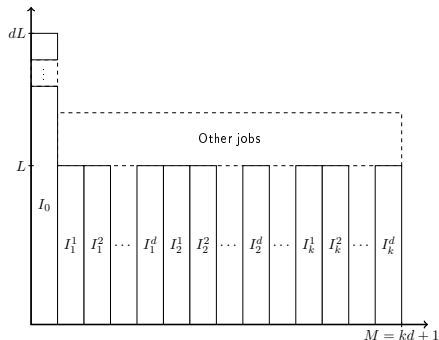


Instance leading to arbitrarily small approximation ratio

Bad list algorithm approximation ratio for large L



List algorithm schedule



Optimal schedule

Resource leveling (main) criteria

u_t = resource consumption at time step t

- Total overload cost ($=F$)
- Resource Investment cost: Minimize $\max_t u_t$
- Square resource used: Min $\sum_t u_t^2$ (or its variant $\sum_t (u_t - L, 0)^2$).
- Absolute variations: $\sum_t |u_{t+1} - u_t|$
- Squared absolute variations: $\sum_t (u_{t+1} - u - t)^2$

Usually considered for problems with multiple resources (RCPSP)

Some related works

- P. Györgyi, T. Kis, A common approximation framework for early work, late work, and resource leveling problems, EJOR (2020). → A PTAS for $L|C_{max} \leq M|F$.
- S. Hartmann, D. Briskorn. An updated survey of variants and extensions of the resource-constrained project scheduling problem, EJOR (2022). → Review on RCPSP, including resource leveling.